

Απαντήσεις στα θέματα φυσικής θετικής κατεύθυνσης

Θέμα Α

A1. α

A2. β

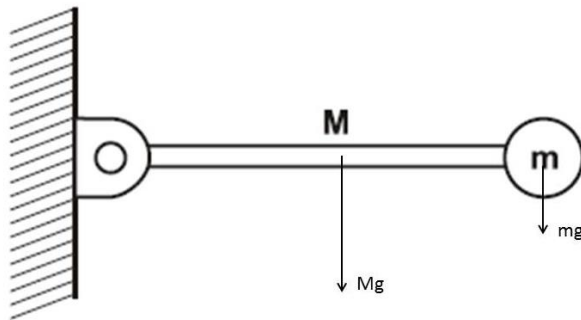
A3. α

A4. δ

A5. α) Λ β) Σ γ) Σ δ) Λ ε) Σ

Θέμα Β

B1. iii)



$$I_{o\lambda} = I_p + ml^2$$

$$I_{o\lambda} = \frac{1}{3}ML^2 + \frac{1}{2}ML^2 = \frac{5}{6}ML^2$$

$$\left. \begin{aligned} \Sigma\tau &= I_{o\lambda} \cdot a_\gamma \\ \Sigma\tau &= Mg\frac{L}{2} + mgL \end{aligned} \right\} \Rightarrow$$

$$I_{o\lambda} \cdot a_\gamma = Mg\frac{L}{2} + \frac{Mg}{2}L$$

$$I_{o\lambda} \cdot a_\gamma = MgL$$

$$\frac{5}{6}ML^2 \cdot a_\gamma = MgL$$

$$a_\gamma = \frac{6g}{5L}$$

$$\frac{\Delta L_{\rho}}{\Delta t} = I_{\rho} \cdot a_{\gamma} = \frac{1}{3} ML^2 \cdot \frac{6g}{5L} = \frac{2}{5} MgL$$

B2. iii)

$$y = 2A \sigma \nu \nu \left(\frac{2\pi x}{\lambda} \right) \eta \mu \left(\frac{2\pi t}{T} \right)$$

Από την εξίσωση του στάσιμου παρατηρούμε ότι έχουμε κοιλία στο Ο.

$$\text{Επομένως: } X_{\Delta} = (2\kappa + 1) \frac{\lambda}{4} \stackrel{\kappa=2}{\implies} X_{\Delta 3} = \frac{5\lambda}{4}$$

$$X_M = X_{\Delta 3} + \frac{\lambda}{12} = \frac{5\lambda}{4} + \frac{\lambda}{12} = \frac{4\lambda}{3}$$

$$A'_M = 2A \left| \sigma \nu \nu \frac{2\pi x_M}{\lambda} \right| \implies$$

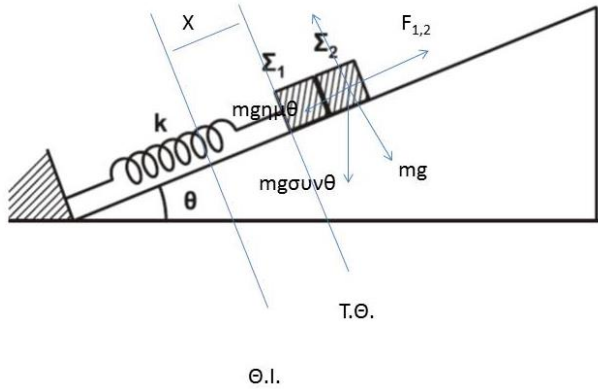
$$A'_M = 2A \left| \sigma \nu \nu \left(\frac{2\pi \frac{4\lambda}{3}}{\lambda} \right) \right| \implies$$

$$A'_M = 2A \left| \sigma \nu \nu \left(\frac{8\pi}{3} \right) \right| \implies$$

$$A'_M = 2A \left| \sigma \nu \nu \left(\frac{2\pi}{3} \right) \right| \implies$$

$$A'_M = A$$

B3. i)



Για λείο κεκλιμένο επίπεδο

$$\kappa = D_{ολ} = (m_1 + m_2)\omega^2$$

$$\omega = \sqrt{\frac{\kappa}{m_1 + m_2}}$$

$$D_2 = m_2\omega^2$$

Η πιθανή αποκόλληση θα συμβεί πάνω από τη θέση ισορροπίας .

Για μια τυχαία θέση πάνω από τη ΘΙ ισχύει :

$$\left. \begin{aligned} \Sigma F_2 &= D_2 x \\ \Sigma F_2 &= m_2 g \eta \mu \theta - F_{1,2} \end{aligned} \right\} \Rightarrow$$

$$D_2 x = m_2 g \eta \mu \theta - F_{1,2}$$

$$F_{1,2} = m_2 g \eta \mu \theta - D_2 x$$

$$F_{1,2} = m_2 g \eta \mu \theta - m_2 \frac{\kappa}{m_1 + m_2} x \xrightarrow{F_{1,2}=F_{1,2 \min} \text{ και } X=A}$$

$$F_{1,2 \min} = m_2 g \eta \mu \theta - m_2 \frac{\kappa}{m_1 + m_2} A$$

$$\theta \acute{\epsilon}\lambda\omega F_{1,2 \min} > 0$$

$$m_2 g \eta \mu \theta - m_2 \frac{\kappa}{m_1 + m_2} A > 0$$

$$(m_1 + m_2) g \eta \mu \theta > \kappa A$$

$$\kappa A < (m_1 + m_2) g \eta \mu \theta$$

Θέμα Γ

Γ1.

Α.Δ.Ε.Τ.

$$U_E + U_B = E_T$$

$$U_E = \frac{1}{2}L(I^2 - i^2) \quad (1)$$

$$U_E = 8 \cdot 10^{-2}(I^2 - i^2) \quad (2)$$

$$\text{από (1), (2)} \quad \frac{1}{2}L = 8 \cdot 10^{-2} \Rightarrow$$

$$L = 16 \cdot 10^{-2} \text{ H}$$

$$I^2 = 1 \Rightarrow I = 1 \text{ A}$$

$$U_{E_{\max}} = U_{B_{\max}} = \frac{1}{2}LI^2 = 8 \cdot 10^{-2} \text{ J}$$

$$E_T = U_{E_{\max}} = \frac{1}{2}CV_C^2 \Rightarrow C = \frac{2E_T}{V_C^2} = 10^{-4} \text{ F}$$

$$T = 2\pi\sqrt{LC} = 8\pi 10^{-3} \text{ s}$$

Γ2.

$$E_T = \frac{1}{2}LI^2 = 8 \cdot 10^{-2} \text{ J}$$

$$U_E = E_T \sigma \nu^2 (\omega t) \Rightarrow$$

$$U_E = E_T \sigma \nu^2 \left(\frac{2\pi}{T} \cdot \frac{T}{12} \right) \Rightarrow$$

$$U_E = E_T \sigma \nu^2 \left(\frac{\pi}{6} \right) \Rightarrow$$

$$U_E = 6 \cdot 10^{-2} \text{ J}$$

Γ3.

$$E_T = U_E + U_B \quad (1)$$

$$U_E = 3U_B \Rightarrow U_B = \frac{U_E}{3} \quad (2)$$

από(1),(2)

$$E_T = U_E + \frac{U_E}{3} \Rightarrow$$

$$E_T = \frac{4}{3}U_E \Rightarrow$$

$$E_T = \frac{4}{3} \frac{1}{2} \frac{q^2}{C} \Rightarrow q = \sqrt{\frac{3E_T C}{2}} \Rightarrow$$

$$q = \pm 2\sqrt{3}10^{-3} C$$

$$\left| \frac{di}{dt} \right| = \left| -\frac{E_{\text{ΑΥΤ}}}{L} \right| = \left| -\frac{V_C}{L} \right| = \left| -\frac{q}{LC} \right| = \frac{\sqrt{3}}{8} 10^3 \frac{A}{s}$$

Γ4.

$$\omega = \frac{2\pi}{T} \Rightarrow \omega^2 = \frac{4\pi^2}{T^2} \Rightarrow \omega^2 = \frac{1}{16 \cdot 10^{-6}} \quad (S.I)$$

$$\omega = \frac{1}{\sqrt{LC}} \Rightarrow LC = \frac{1}{\omega^2} \Rightarrow LC = 16 \cdot 10^{-6} \quad (S.I)$$

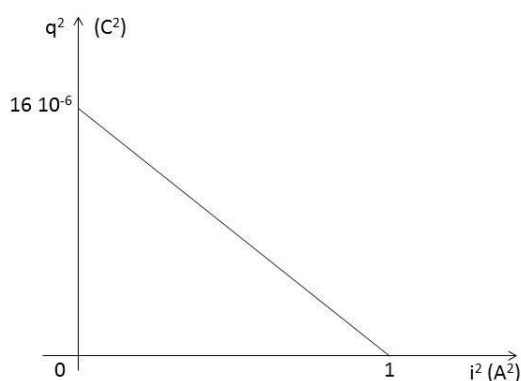
$$E_T = U_E + U_B \Rightarrow U_E = E_T - U_B \Rightarrow$$

$$\frac{1q^2}{2c} = \frac{1}{2} Li^2 - \frac{1}{2} Li^2 \Rightarrow$$

$$q^2 = LCi^2 - LCi^2 \Rightarrow$$

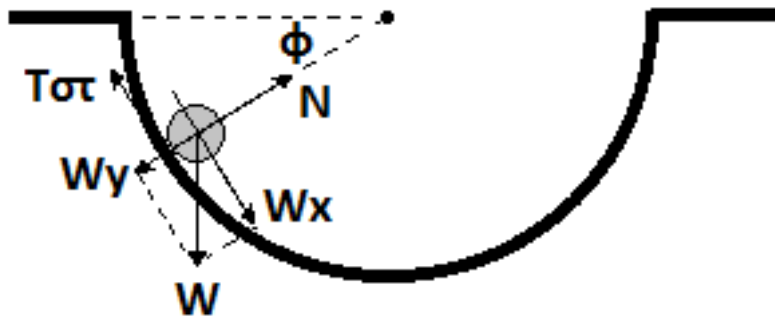
$$q^2 = 16 \cdot 10^{-6} - 16 \cdot 10^{-6} i^2 \quad (S.I)$$

$$(\mu\epsilon - 1 \leq i \leq +1 \Rightarrow 0 \leq i^2 \leq +1)$$



Θέμα Δ

Δ1.



$$\left\{ \begin{array}{l} \Sigma F = mg \sigma \nu \nu \varphi - T_s \\ \Sigma F = ma_{cm} \end{array} \right\} \Rightarrow T_s = mg \sigma \nu \nu \varphi - ma_{cm} \quad (1)$$

$$\left\{ \begin{array}{l} \Sigma \tau = I \alpha_\gamma \\ \Sigma \tau = T_s r \end{array} \right\} \Rightarrow$$

$$I \alpha_\gamma = T_s r \Rightarrow$$

$$\frac{2}{5} m r^2 \alpha_\gamma = T_s r \Rightarrow$$

$$\frac{2}{5} m \alpha_{cm} = T_s \Rightarrow$$

$$a_{cm} = \frac{5 T_s}{2 m} \quad (2)$$

$$\text{από (1), (2)} \quad T_s = mg \sigma \nu \nu \varphi - \frac{5}{2} T_s \Rightarrow$$

$$\frac{7}{2} T_s = mg \sigma \nu \nu \varphi \Rightarrow T_s = \frac{2}{7} mg \sigma \nu \nu \varphi \Rightarrow$$

$$T_s = 4 \sigma \nu \nu \varphi (S.I)$$

Δ2.

$$\left. \begin{aligned} \Sigma F_y &= \frac{mu_{cm}^2}{(R-r)} \\ \Sigma F_y &= N - mg\eta\mu\varphi \end{aligned} \right\} \Rightarrow$$

$$\frac{mu_{cm}^2}{(R-r)} = N - mg\eta\mu\varphi \Rightarrow$$

$$N = mg\eta\mu\varphi + \frac{mu_{cm}^2}{(R-r)} \quad (3) \quad \eta\mu\varphi = \frac{h}{R-r}$$

Α.Δ.Μ.Ε. Α→Γ

$$E_A = E_\Gamma$$

$$mgh = \frac{1}{2}mu_{cm}^2 + \frac{1}{2}I\omega^2$$

$$mg(R-r)\eta\mu\varphi = \frac{1}{2}mu_{cm}^2 + \frac{1}{2}mr^2\omega^2$$

$$g(R-r)\eta\mu\varphi = \frac{1}{2}u_{cm}^2 + \frac{1}{5}u_{cm}^2$$

$$g(R-r)\eta\mu\varphi = \frac{7}{10}u_{cm}^2$$

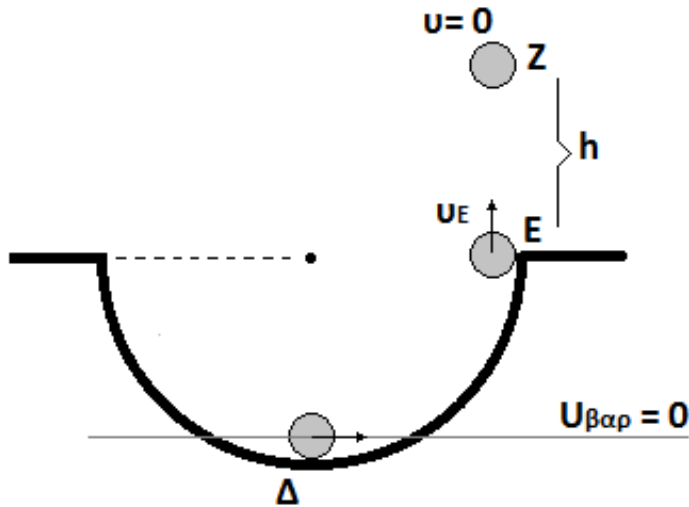
$$u_{cm}^2 = \frac{10}{7}g(R-r)\eta\mu\varphi \quad (4)$$

$$(3) \xrightarrow{(4)} N = mg\eta\mu\varphi + \frac{10}{7} \frac{m}{(R-r)} g(R-r)\eta\mu\varphi$$

$$N = \frac{17}{7}mg\eta\mu\varphi$$

$$N=17N$$

Δ3.



Α.Δ.Μ.Ε. (Δ) → (Ε)

$$E_{\Delta} = E_E \Rightarrow$$

$$\frac{1}{2} m u_{\Delta}^2 + \frac{1}{2} I \omega_{\Delta}^2 = mg(R-r) + \frac{1}{2} m u_E^2 + \frac{1}{2} I \omega_E^2 \Rightarrow$$

$$m u_{\Delta}^2 + \frac{2}{5} m r^2 \omega_{\Delta}^2 = 2mg \frac{7}{8} R + m u_E^2 + \frac{2}{5} m r^2 \omega_E^2$$

$$\frac{u_{\Delta} = \omega_{\Delta} r}{u_E = \omega_E r} \rightarrow \frac{7}{5} u_{\Delta}^2 = \frac{7}{4} gR + \frac{7}{5} u_E^2 \Rightarrow$$

$$u_{\Delta}^2 - \frac{5}{4} gR = u_E^2 \Rightarrow u_E^2 = 36 - \frac{5}{4} \cdot 10 \cdot 1.6$$

$$u_E^2 = 36 - 20 \Rightarrow u_E^2 = 16 \Rightarrow$$

$$u_E = 4 \text{ m/s}$$

Α.Δ.Μ.Ε. (Ε) → h_{\max} (θέση z)

$$E_E = E_Z \Rightarrow$$

$$\frac{1}{2} m u_E^2 + \frac{1}{2} I \omega_E^2 = mgh_{\max} + \frac{1}{2} I \omega_E^2 \Rightarrow$$

$$h_{\max} = \frac{u_E^2}{2g} \Rightarrow h_{\max} = \frac{16}{20} \Rightarrow$$

$$h_{\max} = 0.8 \text{ m}$$

Δ4.

Αμέσως μετά την απώλεια επαφής στο Ε :



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$$\Sigma\tau=0$$

$$\frac{dK}{dt} = \frac{dw}{dt} = \Sigma F \cdot v + \Sigma\tau \cdot \omega = -mgu_E + 0 = -1,4 \cdot 10 \cdot 4 = -56 \text{ J/s}$$

$$\frac{dL}{dt} = \Sigma\tau = 0 \quad (\text{Η ροπή του βάρους είναι μηδέν})$$

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